

**APPENDIX**  
**VERSION WITH MARKINGS TO SHOW CHANGES MADE**

**IN THE SPECIFICATION:**

The paragraph beginning on page 3, line 12 is amended as follows:

The first-axis servo motor 105 is provided with a rotary encoder 107 as a motor position detector for detecting a rotational position (motor position) thereof, and the ~~first-axis~~ second-axis servo motor 106 is provided with a rotary encoder 108 as a motor position detector for detecting a rotational position (motor position) thereof.

**IN THE CLAIMS:**

Claims 1-8 are amended as follows:

1. (Amended) A position control method for feed drive equipment in which a plurality of feed drive mechanisms disposed in parallel for feeding a movable body are individually driven by servo motors, the position control method comprising:

~~detecting~~ determining torque of the servo motors, and

correcting position commands of at least one servo motor ~~the servo motors~~ in dependence on the ~~detected~~ determined torque so that the servo motors have matching torque.

2. (Amended) A position control method for feed drive equipment according to claim 1, wherein torque of the servo motors are matched to an average of the ~~detected~~ determined torque.

3. (Amended) A position control method for feed drive equipment according to claim 1, wherein torque of one servo motor is matched to the ~~detected~~ determined torque of another servo motor.

4. (Amended) A position control method for feed drive equipment according to claim 1, wherein a value of a torque command to be input to a current controller of each servo motor is ~~detected~~ determined as the torque of the servo motor.

5. (Amended) A position control system for feed drive equipment in which a plurality of feed drive mechanisms disposed in parallel for feeding a movable body are individually driven by servo motors, the position control system comprising:

a controller for ~~detecting~~ determining torque of the servo motors, and correcting position commands of at least one servo motor ~~the servo motors~~ in dependence on the ~~detected~~ determined torque so that the servo motors have matching torque.

6. (Amended) A position control system for feed drive equipment according to claim 5, wherein the controller makes torque of the servo motors match to an average of the ~~detected~~ determined torque.

7. (Amended) A position control system for feed drive equipment according to claim 5, wherein the controller makes torque of one servo motor match to the ~~detected~~ determined torque of another servo motor.

8. (Amended) A position control system for feed drive equipment according to claim 5, wherein the controller ~~detects~~ determines a value of a torque command to be input to a current controller of each servo motor, as the torque of the servo motor.

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